

(1)

Solutions to review questions
For exam 1

(1.1)

1. A vector is a displacement between point a (where the particle began its journey) and point b (where the particle ended its journey). A point is simply the particle's position in space.

2. Instead of describing a curve or a surface in terms of the coordinate axes, the curve or surface may sometimes be more simply described with a different set of variables.

For example $P = \{(s+2t-1, t, 4s+2) : s, t \in \mathbb{R}\}$ is a plane spanned by the vectors $(1, 0, 4)$ and $(2, 1, 0)$. This plane looks just like the xy plane to any pedestrian walking on it. However, the positions on the plane relative to the xyz coordinate system are given by $(x, y, z) = (x(s, t), y(s, t), z(s, t))$ where $x(s, t) = s+2t-1$, $y(s, t) = t$, and $z(s, t) = 4s+2$.

3. $L(t) = (1, 0, -3) + t(-3, -10, 1) = (1-3t, -10t, -3+t)$.

This line is the Set $L = \{(x, y, z) : (x, y, z) = (1-3t, -10t, -3+t), t \in \mathbb{R}\}$

$L(t)$ represents the position at time t of the particle that is tracing this line.

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4. To be parallel, this line must have direction vector that is a non-zero scalar multiple of the direction vector of $h(t)$ (Ex. 3). Thus, we may take $-3i - 10j + k = (-3, -10, 1)$ to be the direction vector,

The desired line is parametrized by $S(t) = (1, 1, 1) + t(-3, -10, 1)$

5. Two lines are perpendicular iff their directional vectors are perpendicular. There are infinitely many vectors that are perpendicular to $(-3, -10, 1)$ and infinitely many lines through $(1, 0, -3)$ that are perpendicular to the line from (Ex. 3). Take $\vec{n} = (0, 1, 10)$. Then $\vec{n} \cdot (-3, -10, 1) = (0, 1, 10) \cdot (-3, -10, 1) = 0$ Hence $\vec{n} \perp (-3, -10, 1)$. It follows that the line through $(1, 0, -3)$ in the direction \vec{n} is perpendicular to the line from (Ex. 3): $P(t) = (1, 0, -3) + t(0, 1, 10)$ is a parametrization of this line.

(Note that the solution is not unique. It would have been unique if we asked to find a perpendicular line through $(1, 0, -3)$ that intersects the line in (Ex. 3).)

$$6. (1, 0, -3) + t((6, 7, 6) - (1, 0, -3)) = (1, 0, -3) + t(5, 7, 9) = h(t)$$

Note that $h(0) = (1, 0, -3)$ and $h(1) = (6, 7, 6)$. Thus, the particle that parametrizes this line will be observed in position $(1, 0, -3)$ at present time, in 1 time unit, the particle will have traveled to position $(6, 7, 6)$.

What is a parametrization $p(t)$ s.t. $p(0) = (6, 7, 6)$ and $p(1) = (1, 0, -3)$?

$P(t)$ is another solution.

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7. $L(t)$ has direction $(-1, 1, 1)$ and $p(t)$ has direction $(3, 1, 2)$

Since $(-1, 1, 1) \cdot (3, 1, 2) = -3 + 1 + 2 = 0$, the lines are perpendicular to each other.

To see whether or not the lines intersect, set $L(t) = p(s)$:

$$(-2-t, 3+t, -2+t) = (-1+3s, 2+s, -3+2s) \Rightarrow$$

$$-2-t = -1+3s$$

$$3+t = 2+s$$

$$-2+t = -3+2s$$

The last equation implies that $t = -1+2s$. Substituting in the middle equation, we get $3+(-1+2s) = 2+s$ or $2s = s \Rightarrow s = 0 \Rightarrow t = -1$. Checking:

$$-2-(-1) \stackrel{?}{=} -1+3 \cdot 0 \quad \checkmark$$

$$3-1 \stackrel{?}{=} 2+0 \quad \checkmark$$

$$-2-1 \stackrel{?}{=} -3+2 \cdot 0 \quad \checkmark$$

Thus the lines traced by $p(t)$ and $L(t)$ intersect but the particles that traced them do not collide (why?).

$$8. P = \{(0, 1, -6) + s(2, 1, -4) + t(-3, -5, 2) : s, t \in \mathbb{R}\} =$$

$$= \{(2s-3t, 1+s-5t, -6-4s+2t) : s, t \in \mathbb{R}\}$$

9. S is spanned (generated) by the vectors $(2, -1, 7)$ and $(-6, 3, -21) = -3(2, -1, 7)$. Since the latter is a scalar multiple of the first vector, the two vectors are linearly dependent.

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Consequently S is really a line.

Alternative solution:

Let $u = s - 3t$ then $(2s - 6t + 1, 3t - s, 7s - 21t + 4) =$
 $= (2(s - 3t) + 1, -(s - 3t), 7(s - 3t) + 4) = (2u + 1, -u, 7u + 4) =$
 $= (1, 0, 4) + u(2, -1, 7) = L(u)$ note that $L(u)$ is a parametrization
of a line through $(1, 0, 4)$ with direction vector $(2, -1, 7)$.

$$10. S = \{(-1, -4, 7) + r(1, 0, 1) + s(2, 2, 0) + t(0, 3, 3)\}$$

Since $r, s \in [0, 1]$ and $t \in [0, 2]$, S is the parallelepiped spanned
by the vectors $(1, 0, 1)$, $(2, 2, 0)$, and $2(0, 3, 3) = (0, 6, 6)$ with
corner at $(-1, -4, 7)$.

(1.2)

1. Review the notes. Ask yourself "what is proportionality?"

$$2. (2, 1, -4) \cdot (-3, -5, 2) = -6 - 5 - 8 = -19$$

$$3. \theta = \cos^{-1} \left(\frac{-19}{\|(2, 1, -4)\| \|(-3, -5, 2)\|} \right) = \cos^{-1} \left(\frac{-19}{\sqrt{21} \sqrt{38}} \right)$$

$$4. \frac{(2, 1, -4)}{\|(2, 1, -4)\|} = \frac{1}{\sqrt{21}} (2, 1, -4) \equiv \text{unit vector in the direction of}$$

$$v = (2, 1, -4); \quad \frac{-1}{\sqrt{21}} (2, 1, -4) \equiv \text{unit vector in the opposite direction}$$

$$5. p_w(v) = p_{(-3, -5, 2)}(2, 1, -4) = \frac{(2, 1, -4) \cdot (-3, -5, 2)}{\|(-3, -5, 2)\|^2} (-3, -5, 2) =$$

$$= \frac{-19}{38} (-3, -5, 2)$$

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6. Two vectors are linearly dependent if they generate the same line. Mathematically, \vec{v}, \vec{w} are linearly dependent if there exist scalars $a, b \in \mathbb{R}$ that are not both 0 s.t., $a\vec{v} + b\vec{w} = \vec{0}$.

Three vectors $\vec{v}, \vec{w}, \vec{u}$ are linearly dependent if they all lie on the same plane. Mathematically, if there are scalars $a, b, c \in \mathbb{R}$, not all 0 s.t., $a\vec{v} + b\vec{w} + c\vec{u} = \vec{0}$.

7. Review lecture notes for the proof, Triangle inequality states, in geometric terms, that the shortest distance between any two points in Euclidean space is the length of the line segment connecting them.

(6.3)

1. Review lecture notes,

$$2. \begin{vmatrix} 2 & 2 & 0 \\ -3 & 0 & -3 \\ 0 & 5 & 5 \end{vmatrix} = 2 \begin{vmatrix} 0 & -3 \\ 5 & 5 \end{vmatrix} - 2 \begin{vmatrix} -3 & -3 \\ 0 & 5 \end{vmatrix} + 0 \begin{vmatrix} -3 & 0 \\ 0 & 5 \end{vmatrix} =$$

$= 2 \cdot 15 + 2 \cdot 15 = 4 \cdot 15 = 60$ since the volume is just the absolute value of the determinant, the answer is 60.

$$3. \begin{vmatrix} n & n+1 & n+2 \\ n+3 & n+4 & n+5 \\ n+6 & n+7 & n+8 \end{vmatrix} = \begin{vmatrix} n & n+1 & n+2 \\ 3 & 3 & 3 \\ 3 & 3 & 3 \end{vmatrix} = 0$$

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$$4. \begin{vmatrix} 3a_{21} & 3a_{22} & 3a_{23} \\ a_{11} & a_{12} & a_{13} \\ b_{31}-a_{31} & b_{32}-a_{32} & b_{33}-a_{33} \end{vmatrix} = \begin{vmatrix} 3a_{21} & 3a_{22} & 3a_{23} \\ a_{11} & a_{12} & a_{13} \\ b_{31} & b_{32} & b_{33} \end{vmatrix} -$$

$$- \begin{vmatrix} 3a_{21} & 3a_{22} & 3a_{23} \\ a_{11} & a_{12} & a_{13} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = -3 \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ b_{31} & b_{32} & b_{33} \end{vmatrix} +$$

$$+ 3 \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = 3(-1 + (-4)) = 3(-5) = -15$$

5. the triangle has "edge vectors" $\vec{v} = (3,3) - (1,1) = (2,2)$ and $\vec{w} = (2,6) - (1,1) = (1,5)$. The area of the triangle is half the area of the parallelogram with corresponding edges:

$$\frac{1}{2} |\det \begin{pmatrix} 2 & 2 \\ 1 & 5 \end{pmatrix}| = \frac{1}{2} |2 \det \begin{pmatrix} 1 & 1 \\ 1 & 5 \end{pmatrix}| = | \begin{vmatrix} 1 & 1 \\ 1 & 5 \end{vmatrix} | = 5 - 1 = 4$$

6. Review lecture notes.

$$7. \begin{vmatrix} i & j & k \\ 2 & 2 & 0 \\ -3 & 0 & -3 \end{vmatrix} = -6i + 6j + 6k = (-6, 6, 6)$$

$$-2b \times a = -2(b \times a) = -2(-1)(a \times b) = 2(a \times b) = (-12, 12, 12)$$

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8. Let $\vec{v} = (-1, 0, 1) - (1, 1, 1) = (-2, -1, 0)$ and $\vec{w} = (0, 2, 3) - (1, 1, 1) = (-1, 1, 2)$

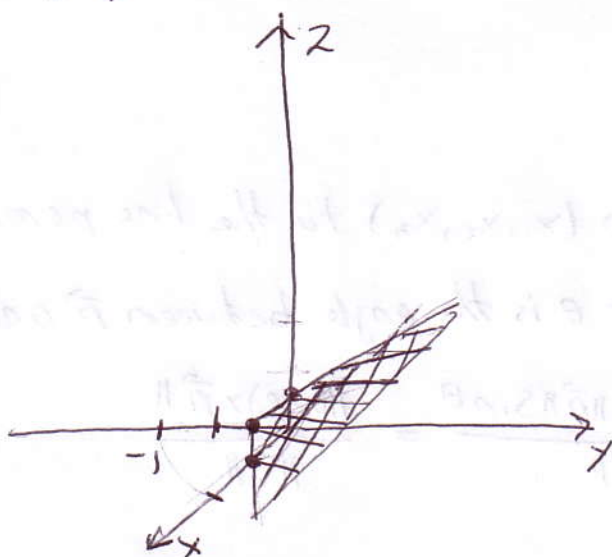
$$\text{Define } \vec{n} = \vec{v} \times \vec{w} = \begin{vmatrix} i & j & k \\ -2 & -1 & 0 \\ -1 & 1 & 2 \end{vmatrix} = -2i + 4j - 3k = (-2, 4, -3)$$

The desired plane satisfies the equation $\vec{n} \cdot (x-1, y-1, z-1) = 0$
 or $(-2, 4, -3) \cdot (x-1, y-1, z-1) = -2x + 2 + 4y - 4 - 3z + 3 =$
 $= -2x + 4y - 3z + 1 = 0$

Remark: any $\lambda \neq 0$ allows the equation of the plane to be written as $-2\lambda x + 4\lambda y - 3\lambda z + \lambda = 0$.

9. The plane's intersection with the xy plane is the line $-2x + 4y + 1 = 0$ when $y=0$ we see that $(\frac{1}{2}, 0, 0)$ is on the plane. Also, when $x=0$ we see that $(0, -\frac{1}{4}, 0)$ is on the plane,

The plane's intersection with the xz plane is the line $-2x - 3z + 1 = 0$ when $x=0$, we see that $(0, 0, \frac{1}{3})$ is on the plane. These 3 points are sufficient to graph it.



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10. The distance from a point (x_1, y_1, z_1) to the plane with equation $Ax + By + Cz + D = 0$ is $\frac{|Ax_1 + By_1 + Cz_1 + D|}{\sqrt{A^2 + B^2 + C^2}}$

Hence the desired distance is $\frac{|3 \cdot 6 - 5(-10) + 2(3) + 2|}{\sqrt{3^2 + 5^2 + 2^2}} =$
 $= \frac{|18 + 50 + 6 + 2|}{\sqrt{38}} = \frac{76}{\sqrt{38}}$

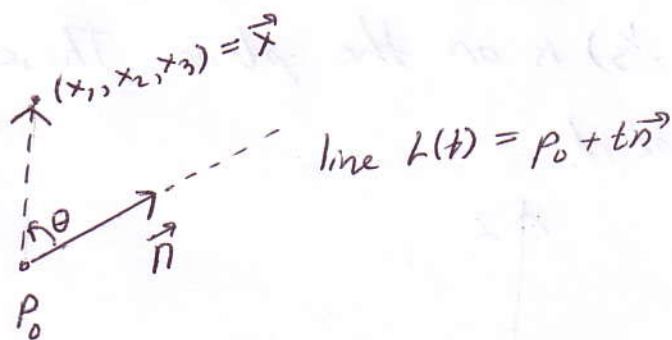
11. $\|v \times w\| = \|v\| \|w\| \sin \theta$ where θ is the angle from v to w .

12. The area of the parallelogram is the norm of the cross product of the vectors that form its sides,

$$\begin{vmatrix} i & j & k \\ 2 & 0 & -1 \\ 0 & 1 & 1 \end{vmatrix} = i - 2j + 2k = (1, -2, 2). \quad \text{The area of given}$$

parallelogram is $\|(1, -2, 2)\| = \sqrt{1 + 4 + 4} = \sqrt{9} = 3$

13.



The distance from (x_1, x_2, x_3) to the line parametrized by $L(t) = P_0 + t\vec{n}$ is $\|x - P_0\| \sin \theta$ where θ is the angle between \vec{n} and $x - P_0$ (why?).

$$\|x - P_0\| \sin \theta = \frac{\|x - P_0\| \|\vec{n}\| \sin \theta}{\|\vec{n}\|} = \frac{\|x - P_0\| \times \|\vec{n}\| \sin \theta}{\|\vec{n}\|}$$

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In our case $\vec{x} = (1, 2, 3)$, $p_0 = (0, 1, 0)$ and $\vec{n} = (1, 2, 1)$.

Therefore $\vec{x} - p_0 = (1, 1, 3)$ and $(\vec{x} - p_0) \times \vec{n} = \begin{vmatrix} i & j & k \\ 1 & 1 & 3 \\ 1 & 2 & 1 \end{vmatrix} =$
 $= -5i + 2j + k = (-5, 2, 1)$

Therefore the distance is $\frac{\|(-5, 2, 1)\|}{\|(1, 2, 1)\|} = \frac{\sqrt{25+4+1}}{\sqrt{1+4+1}} = \frac{\sqrt{30}}{\sqrt{6}}$
 $= \sqrt{\frac{30}{6}} = \sqrt{5}$.

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1. $e_3 = (0, 0, 1, 0, 0)$

2. $a \cdot b = 1 \cdot 3 + 0 \cdot 3 + 4(-1) + (-2)6 = 3 - 4 - 12 = -13$,

3. $AB = \begin{pmatrix} 2 & 1 \\ 4 & 3 \\ 6 & 19 \end{pmatrix}$ BA is undefined.

$3B = \begin{pmatrix} 6 & 15 \\ 0 & 12 \\ 0 & 3 \\ 0 & 3 \end{pmatrix}$ $A - B$ is undefined

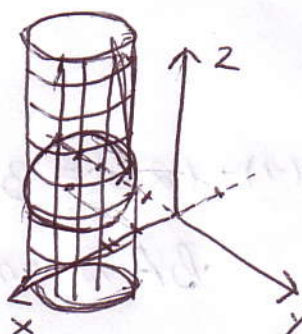
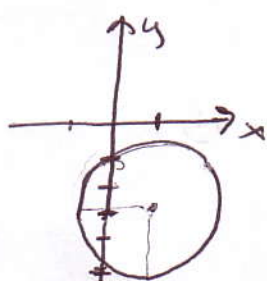
$A^T = \begin{pmatrix} 1 & 2 & 3 \\ -1 & -2 & 0 \\ 1 & 0 & 0 \\ -1 & 1 & 4 \end{pmatrix}$

4. $-2C = \begin{pmatrix} 0 & 2 & 0 & 2 \\ -8 & -16 & 0 & -2 \\ -2 & 0 & 0 & -18 \end{pmatrix}$ so $A - 2C = \begin{pmatrix} 1 & 1 & 1 & 1 \\ -6 & -18 & 0 & -1 \\ 1 & 0 & 0 & -14 \end{pmatrix}$

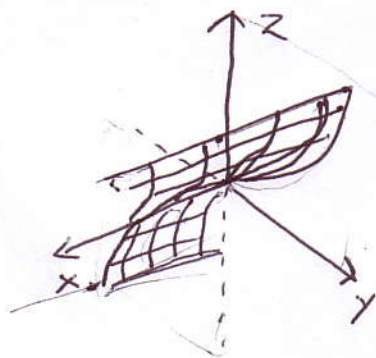
$$A+C = \begin{pmatrix} 1 & -2 & 1 & -2 \\ 6 & 6 & 0 & 2 \\ 4 & 0 & 0 & 13 \end{pmatrix} \quad (10)$$

(2.1)

1. In \mathbb{R}^2 this equation describes a circle with center $c = (1, -3)$ and radius $r = 2$. In \mathbb{R}^3 this is a cylinder generated by projecting this circle along the z -axis.



2. $f(x, y) = y^3$ is a cylinder obtained by projecting the graph of $z = y^3$ in the yz plane along the x -axis.

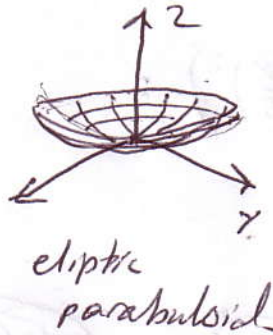
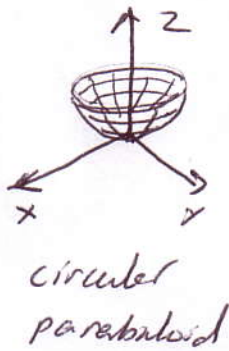


$$3. f(x, y) = x^2 + 2x - 4x + y^2 - 7 = x^2 - 2x + 1 + y^2 - 8 = (x-1)^2 + y^2 - 8$$

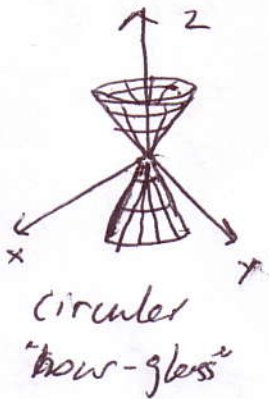
Its graph is a paraboloid shifted so that the lowest point of the "bowl" is at $(1, 0, -8)$

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4. $f(x,y) = \frac{x^2}{9} + \frac{y^2}{25} = \left(\frac{x}{3}\right)^2 + \left(\frac{y}{5}\right)^2$ Therefore its graph is an elliptic paraboloid obtained by stretching a circular paraboloid by a factor of 3 on the x -axis and by a factor of 5 on the y -axis.



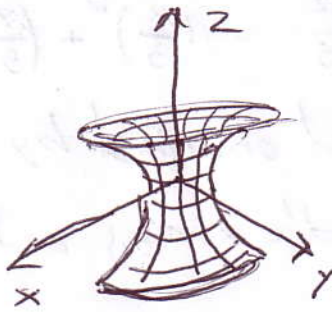
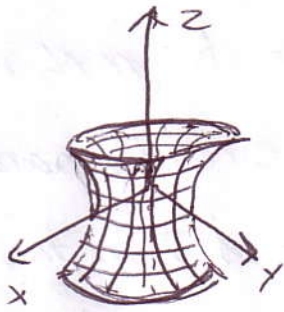
5. This equation can be written as $z^2 = \frac{x^2}{9} + \frac{y^2}{25} \Rightarrow z = \pm \sqrt{\left(\frac{x}{3}\right)^2 + \left(\frac{y}{5}\right)^2}$ which is an elliptic "hour-glass" cone.



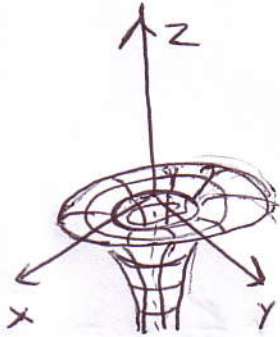
6. This equation can be written as $z^2 = \frac{x^2}{9} + \frac{y^2}{25} - 1 \Rightarrow z = \pm \sqrt{\left(\frac{x}{3}\right)^2 + \left(\frac{y}{5}\right)^2 - 1}$ which is a "circle-into-ellipse" stretch of

$w = \pm \sqrt{u^2 + v^2 - 1}$. The latter curve is a revolution of $w = \pm \sqrt{u^2 - 1}$ about the w -axis. The corresponding graph to $w = \pm \sqrt{u^2 + v^2 - 1}$ is therefore the circular hyperboloid that is deformed into an elliptic hyperboloid.

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7. $f(x, y) = \ln\left(\left(\frac{x}{3}\right)^2 + \left(\frac{y}{5}\right)^2\right)$;



circular worm-hole

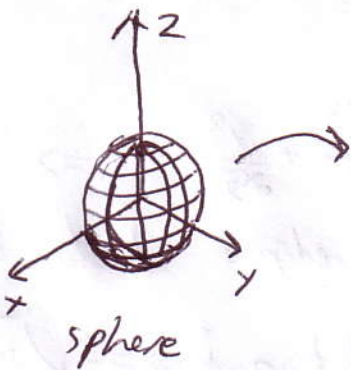


elliptic worm-hole.

8. $(x-3)^2 + (y+2)^2 + (z-1)^2 = 25$

9. $z^2 = 1 - x^2 - \frac{y^2}{4} \Rightarrow z = \pm \sqrt{1 - (x^2 + (\frac{y}{2})^2)}$

or $x^2 + (\frac{y}{2})^2 + z^2 = 1$ which is an ellipsoid ;



sphere

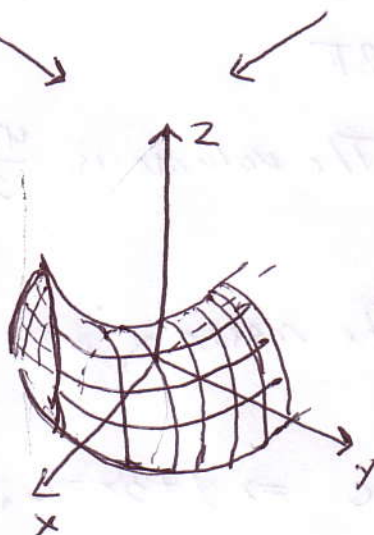
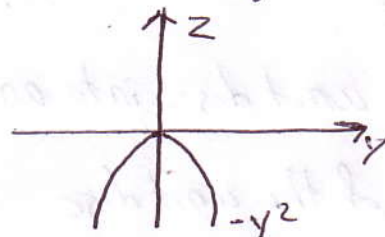
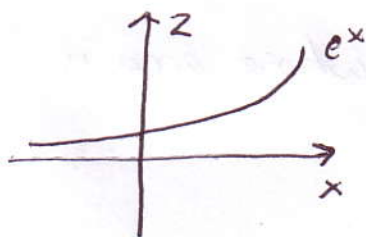


ellipsoid.

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10, $z^4 = (x^2 + y^2)^2 \Rightarrow z^2 = x^2 + y^2 \Rightarrow z = \pm \sqrt{x^2 + y^2}$
 which is a circular "hour-glass" cone.

11, $f(x, y) = e^x - y^2$ is of the form $g(x) + h(y)$ so we can use the "fish and the wine" method to visualize this graph



12. $f(x, y) = \begin{vmatrix} x & y \\ y & x \end{vmatrix} = x^2 - y^2$, we can visualize this

graph by the "fish and wine" method or by describing it in cylindrical coordinates $f(r \cos \theta, r \sin \theta) = r^2 \cos 2\theta$,

13. let $S = \{(x, y) : x^2 + y^2 \leq 1\}$ then S is a circular disc.

let $T(x, y) = (2x, 4y)$ then $T(S) =$

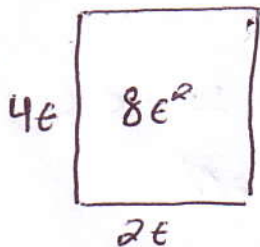
$$= \{(2x, 4y) : x^2 + y^2 \leq 1\} = \{(u, v) : \left(\frac{u}{2}\right)^2 + \left(\frac{v}{4}\right)^2 \leq 1\} = \{(x, y) : \frac{x^2}{4} + \frac{y^2}{16} \leq 1\}$$

$= \{(x, y) : \frac{x^2}{2} + \frac{y^2}{8} \leq 2\}$ which is the elliptical disc of semi-major

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radius 4 and semiminor radius 2.

Since T modifies the square of area $\epsilon^2 \in \boxed{\epsilon^2}$ into a rectangle



with area $8\epsilon^2$ (8 times the area of the square),

T stretches the unit disc into an elliptical disc, whose area is 8 times the area of the unit disc.

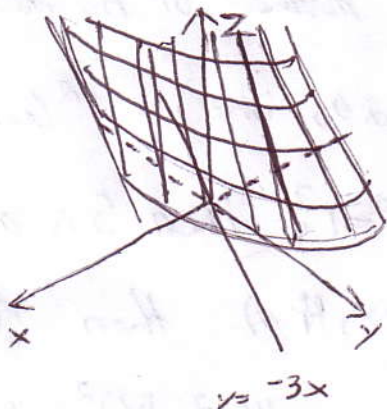
$$\text{Hence } \text{Area}(T(S)) = 8 \text{Area}(S) = 8\pi$$

14. This is similar to (Ex. 13). The volume is $\frac{4\pi}{3} 2 \cdot 3 \cdot 5 = 40\pi$.

15. $\text{Vol}(T(S)) = abc \text{Vol}(S)$ The reasoning was outlined in (Ex. 13),

16. Let $u = y + 3x$. Whenever $u = c \Rightarrow y + 3x = c, y = -3x + c$

Thus $f(x, y) = e^{y+3x}$ is a cylinder with respect to the coordinate system in which the x -axis is replaced by the line $y = -3x$



Linear Transformations

1. A linear map satisfies $T(x+y) = T(x) + T(y)$ &
for any scalar $a \in \mathbb{R}$, $T(ax) = aT(x)$.

Linear maps are generalizations of functions of the form $f(x) = m \cdot x$.

2. $TS(x, y) = T(-y, x-y, 2y) = (x, -2y, 3x-5y)$

ST is undefined, because $T(x, y, z)$ is a vector in \mathbb{R}^3 and is therefore not an element in the domain of S .

3. $6T(x, y, z) = (6x+6y+6z, 12x, 18y-6z)$

$$(T-2U)(x, y, z) = (x+y+z, 2x, 3y-z) - (2x, 2x+2y, 2x+2y-z) \\ = (-x+y+z, -2y, -2x+y+z)$$

$$UT(x, y, z) = U(x+y+z, 2x, 3y-z) = (x+y+z, 3x+y+z, 3x-2y+z)$$

4. $M(T) = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 0 & 0 \\ 0 & 3 & -1 \end{pmatrix}$ $M(S) = \begin{pmatrix} 0 & -1 \\ 1 & -1 \\ 0 & 2 \end{pmatrix}$

$$M(6T) = 6M(T) = 6 \cdot \begin{pmatrix} 1 & 1 & 1 \\ 2 & 0 & 0 \\ 0 & 3 & -1 \end{pmatrix} = \begin{pmatrix} 6 & 6 & 6 \\ 12 & 0 & 0 \\ 0 & 18 & -6 \end{pmatrix}$$

$$M(T-2U) = \begin{pmatrix} -1 & 1 & 1 \\ 0 & -2 & 0 \\ -2 & 1 & 1 \end{pmatrix} \quad M(UT) = \begin{pmatrix} 1 & 1 & 1 \\ 3 & 1 & 1 \\ 3 & -2 & 2 \end{pmatrix} = M(U)M(T)$$

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$$5. (x, y) = T^{-1}(T(x, y)) = T^{-1}(-y, x)$$

$$\text{Thus } T^{-1}(u, v) = (v, -u) \text{ or } T^{-1}(x, y) = (y, -x)$$

$$6. \text{ let } A = \begin{pmatrix} 7 & 3 \\ 2 & 1 \end{pmatrix}, A^{-1} = \frac{1}{7-6} \begin{pmatrix} 1 & -2 \\ -3 & 7 \end{pmatrix}^T = \begin{pmatrix} 1 & -3 \\ -2 & 7 \end{pmatrix}$$

$$B = \begin{pmatrix} -1 & 3 \\ 2 & 3 \end{pmatrix}, B^{-1} = \frac{1}{-3-6} \begin{pmatrix} 3 & -2 \\ -3 & -1 \end{pmatrix}^T = \frac{-1}{9} \begin{pmatrix} 3 & -3 \\ -2 & -1 \end{pmatrix}$$

$$C = \begin{pmatrix} -2 & -6 \\ 1 & 3 \end{pmatrix}, C^{-1} \text{ is undefined because } \det(C) = 0,$$

$$7. T(x, y) = (7x+3y, 2x+y) \equiv \begin{pmatrix} 7 & 3 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = A x^T$$

$$T^{-1}(x, y) \equiv A^{-1} x^T \quad A^{-1} = \frac{1}{7-6} \begin{pmatrix} 1 & -3 \\ -2 & 7 \end{pmatrix} = \begin{pmatrix} 1 & -3 \\ -2 & 7 \end{pmatrix}$$

$$\text{Hence } T^{-1}(x, y) \equiv \begin{pmatrix} 1 & -3 \\ -2 & 7 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \equiv \begin{pmatrix} x-3y \\ -2x+7y \end{pmatrix} \text{ so}$$

$$T^{-1}(x, y) = (x-3y, -2x+7y)$$

$$S(x, y) = (-x+3y, 2x+3y) \equiv \begin{pmatrix} -1 & 3 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = B x^T$$

$$\text{so } S^{-1}(x, y) \equiv \frac{-1}{9} \begin{pmatrix} 3 & -3 \\ -2 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

8. The answer will be revealed to the checker.

(17)

(2.2)

$$1. \lim_{(x,y) \rightarrow (1,2)} \frac{xy - 2x - y + 2}{(x-1)^2 + (y-2)^2} = \lim_{(x,y) \rightarrow (1,2)} \frac{x(y-2) - (y-2)}{(x-1)^2 + (y-2)^2} =$$

$$= \lim_{(x,y) \rightarrow (1,2)} \frac{(x-1)(y-2)}{(x-1)^2 + (y-2)^2} = \lim_{(u,v) \rightarrow (0,0)} \frac{uv}{u^2 + v^2} =$$

$$= \lim_{r \rightarrow 0} \frac{\frac{1}{2} r^2 \sin 2\theta}{r^2} = \lim_{r \rightarrow 0} \sin 2\theta. \quad \text{Since this limit}$$

depends on the angle θ , the limit does not exist.

$$2. \lim_{(x,y) \rightarrow (0,0)} \frac{2x^2y - 2xy^2}{x^2 + y^2} = \lim_{(x,y) \rightarrow (0,0)} 2xy \frac{x-y}{x^2 + y^2} =$$

$$= \lim_{r \rightarrow 0} r^2 \sin 2\theta \frac{r \cos \theta - r \sin \theta}{r^2} = \lim_{r \rightarrow 0} r (\sin 2\theta [\cos \theta - \sin \theta]) = 0$$

Thus the limit exists and is equal to 0,

$$3. 0 \leq \frac{|xyz|}{x^2 + y^2 + z^2} \leq \frac{(\sqrt{x^2 + y^2 + z^2})^3}{(\sqrt{x^2 + y^2 + z^2})^2} = \sqrt{x^2 + y^2 + z^2}$$

$$\text{Hence } \lim_{(x,y,z) \rightarrow (0,0,0)} \frac{xyz}{x^2 + y^2 + z^2} = 0$$

(whenever $\|(x,y,z)\| < \epsilon$ so is $\left| \frac{xyz}{x^2 + y^2 + z^2} - 0 \right|$, because

$$\left| \frac{xyz}{x^2 + y^2 + z^2} - 0 \right| = \frac{|xyz|}{x^2 + y^2 + z^2} \leq \sqrt{x^2 + y^2 + z^2} < \epsilon,$$

(18)

$$4. \lim_{(x,y,z) \rightarrow (2,5,3)} \frac{\sin(4x^2 - 2y + 2z)}{2x^2 - y + 2} = \lim_{u \rightarrow 0} \frac{\sin(2u)}{u} =$$

$$= 2 \lim_{u \rightarrow 0} \frac{\sin(2u)}{2u} = 2, \text{ where } u = 2x^2 - y + 2.$$

$$5. \lim_{(x,y) \rightarrow (0,0)} \frac{e^{2xy} - 1}{y} = \lim_{(x,y) \rightarrow (0,0)} x \frac{e^{2xy} - 1}{xy} =$$

$$= \left(\lim_{u \rightarrow 0} \frac{e^{2u} - 1}{u} \right) \left(\lim_{(x,y) \rightarrow (0,0)} x \right) = \frac{d}{du} (e^{2u}) \Big|_{u=0} \cdot 0 =$$

$$= 0$$

$$6. \lim_{(x,y) \rightarrow (0,0)} \frac{\sin(2x) - 2x + y}{x^3 + y} \Big|_{y=0} = \lim_{x \rightarrow 0} \frac{\sin(2x) - 2x}{x^3}$$

$$\stackrel{*}{=} \lim_{x \rightarrow 0} \frac{2\cos(2x) - 2}{3x^2} \stackrel{*}{=} \lim_{x \rightarrow 0} \frac{-4\sin(2x)}{6x} =$$

$$= -\frac{4}{3}$$

$$\lim_{(x,y) \rightarrow (0,0)} \frac{\sin(2x) - 2x + y}{x^3 + y} \Big|_{y=x^3} = \lim_{x \rightarrow 0} \frac{\sin(2x) - 2x + x^3}{2x^3}$$

$$\stackrel{*}{=} \lim_{x \rightarrow 0} \frac{2\cos(2x) - 2 + 3x^2}{6x^2} \stackrel{*}{=} \lim_{x \rightarrow 0} \frac{-4\sin(2x) + 6x}{12x} =$$

$$= \lim_{x \rightarrow 0} \frac{-4}{6} \frac{\sin 2x}{2x} + \frac{1}{2} = \frac{-2}{3} + \frac{1}{2} = \frac{3}{6} - \frac{4}{6} = -\frac{1}{6}$$

Since $-\frac{4}{3} \neq -\frac{1}{6}$ the limit does not exist.

(19)

$$7. \lim_{(x,y,z) \rightarrow (0,0,0)} \frac{2x^2y \cos z}{x^2+y^2} = 0 \text{ because}$$

$$0 \leq \left| \frac{2x^2y \cos z}{x^2+y^2} \right| \leq \frac{2x^2|y|}{x^2+y^2} \leq \frac{2(x^2+y^2)}{x^2+y^2} |y| = 2|y| \leq 2\sqrt{x^2+y^2}$$

$$\text{Hence } \left| \frac{2x^2y \cos z}{x^2+y^2} \right| \leq \epsilon \text{ whenever } \|(x,y)\| < \frac{\epsilon}{2}.$$

$$8. \lim_{(x,y) \rightarrow (0,0)} \frac{\cos x - 1 - (x^2/2)}{x^4+y^4} \Big|_{y=x} = \lim_{x \rightarrow 0} \frac{\cos x - 1 - (x^2/2)}{2x^4} =$$

$$\stackrel{*}{=} \lim_{x \rightarrow 0} \frac{-\sin x - x}{8x^3} \stackrel{*}{=} \lim_{x \rightarrow 0} \frac{-\cos x - 1}{8 \cdot 3x^2} \rightarrow \frac{-2}{0} = \infty$$

$$\lim_{(x,y) \rightarrow (0,0)} \left| \frac{\cos x - 1 - (x^2/2)}{x^4+y^4} \right| \geq \lim_{(x,y) \rightarrow (0,0)} \left| \frac{\cos x - 1 - (x^2/2)}{2(x^2+y^2)^2} \right| =$$

$$\lim_{r \rightarrow 0} \left| \frac{\cos(r \cos \theta) - 1 - r^2/2 \cos^2 \theta}{2r^4} \right| \stackrel{*}{=} \lim_{r \rightarrow 0} \left| \frac{-\sin(r \cos \theta) \cos \theta - r \cos^2 \theta}{8r^3} \right|$$

$$\stackrel{*}{=} \lim_{r \rightarrow 0} \left| \frac{-\cos(r \cos \theta) \cos^2 \theta - \cos^2 \theta}{8 \cdot 3 r^2} \right| = \frac{\cos^2 \theta}{8 \cdot 3} \lim_{r \rightarrow 0} \left| \frac{\cos(r \cos \theta) - 1}{r^2} \right|$$

$$= \infty \text{ Hence } \lim_{(x,y) \rightarrow (0,0)} \frac{\cos x - 1 - (x^2/2)}{x^4+y^4} = \infty$$

$$9. \lim_{(x,y) \rightarrow (0,0)} \frac{(x-y)^2}{x^2+y^2} \Big|_{y=0} = \lim_{x \rightarrow 0} \frac{x^2}{x^2} = 1 \text{ while}$$

$$\lim_{(x,y) \rightarrow (0,0)} \frac{(x-y)^2}{x^2+y^2} \Big|_{x=y} = \lim_{x \rightarrow 0} \frac{0}{2x^2} = 0 \text{ so lim does not exist}$$

$$10, \lim_{(x,y,z) \rightarrow (2,5,1)} (20) \quad 4x - 3y + 2 = 4 \cdot 2 - 3 \cdot 5 + 1 = -6$$

To prove this, note that $|4x - 3y + 2 - (4 \cdot 2 - 3 \cdot 5 + 1)| =$
 $= |4(x-2) - 3(y-5) + 1(z-1)| \leq \|(4, -3, 1)\| \|(x-2, y-5, z-1)\|$

Hence $|4x - 3y + 2 + 6| < \epsilon$ whenever $\|(x-2, y-5, z-1)\| < \frac{\epsilon}{\|(4, -3, 1)\|}$

so set $\delta(\epsilon) = \frac{\epsilon}{\|(4, -3, 1)\|}$

11. The same line of reasoning as in (Ex 10) works.

$$12. \|(7x + 2y + 8z - 14, x - y - 2 + 1)\| = \|(7(x-0) + 2(y+1) + 8(z-2), (x-0) - (y+1) - (z-2))\|$$

$$\leq |7(x-0) + 2(y+1) + 8(z-2)| + |(x-0) - (y+1) - (z-2)| \leq$$

$$\leq \|(7, 2, 8)\| \|(x, y+1, z-2)\| + \|(1, -1, -1)\| \|(x, y+1, z-2)\| =$$

$$= (\|(7, 2, 8)\| + \|(1, -1, -1)\|) \|(x, y+1, z-2)\| < \epsilon$$

so you could set $\delta(\epsilon) = \frac{\epsilon}{\|(7, 2, 8)\| + \|(1, -1, -1)\|}$